



Audit Games

Anupam Datta

Carnegie Mellon University

February 2013

Repositories of Personal Information



Google

facebook

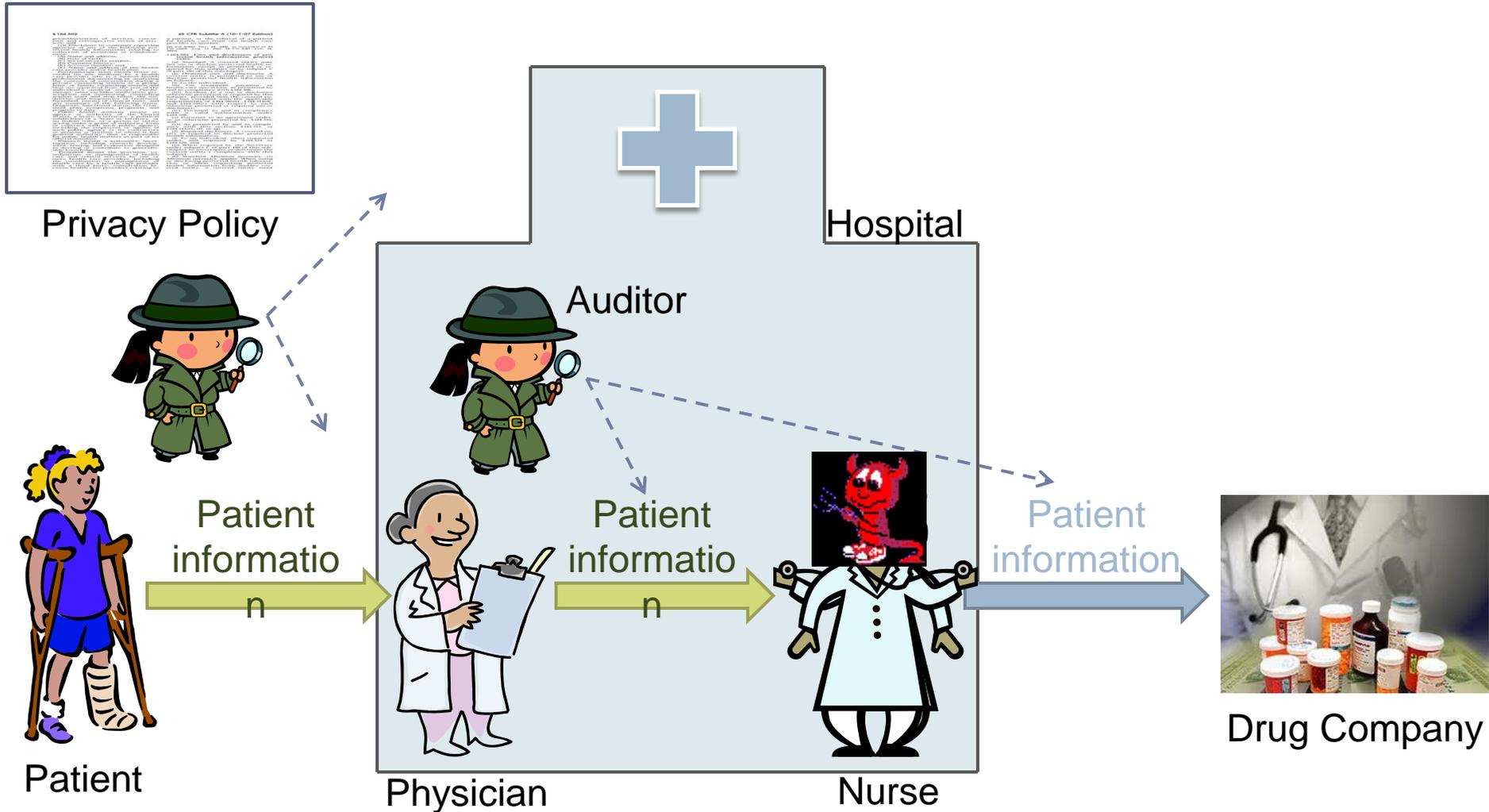


amazon.com



flickr® from YAHOO!

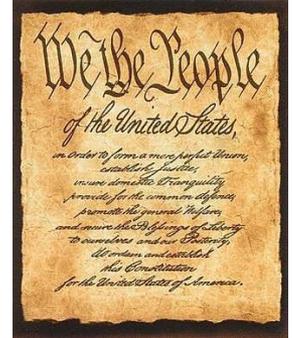
Healthcare Privacy



A Research Area

- ▶ Formalize Privacy Policies
 - ▶ Precise definitions of privacy concepts (restrictions on information flow)
 - ▶ Information used *only for a purpose*
 - ▶ All disclosure clauses in HIPAA & GLBA

- ▶ Enforce Privacy Policies
 - ▶ Audit and Accountability
 - ▶ Detect violations of policy
 - ▶ Identify agents to blame for policy violations
 - ▶ **Resource allocation for inspections and punishments (economic considerations)**



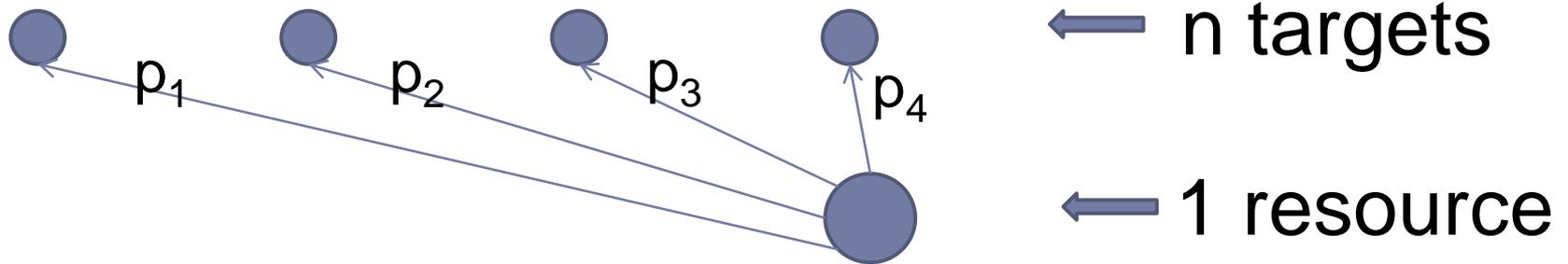
Project page: [Privacy, Audit and Accountability](#)

Play in Three Acts

1. Rational Adversary Setting 
2. Byzantine Adversary Setting
3. Research Directions

[Blocki, Christin, Datta, Procaccia, Sinha; 2013]

Audit Game Model [BCDPS'13]



- ▶ If a violation is found, adversary is fined
- ▶ Utility when target t_i is attacked
 - Defender: $p_i U_{a,D}(t_i) + (1 - p_i)U_{u,D}(t_i) - ax$
 - Adversary: $p_i (U_{a,A}(t_i) - x) + (1 - p_i)U_{u,A}(t_i)$

Price of punishment
[Becker'68]

Stackelberg Equilibrium Concept

- ▶ Defender commits to a randomized resource allocation strategy
- ▶ Adversary plays best response to that strategy

- ▶ Appropriate equilibrium concept
 - ▶ Known defender strategy avoids security by obscurity
 - ▶ Predictable adversary response

- ▶ Goal
 - ▶ Compute optimal defender strategy

Related Work

- ▶ Security resource allocation games [Tambe et al. 2007-]
 - ▶ Computes Stackelberg equilibrium
 - ▶ Deployed systems for resource allocation for patrols at LAX airport, federal air marshals service; under evaluation by TSA, US coast guard

- ▶ Audit games generalize security resource allocation games with the punishment parameter
 - ▶ Computing Stackelberg equilibrium becomes more challenging
 - ▶ Applicable to similar problems

Computing Optimal Defender Strategy

Solve optimization problems P_i for all $i \in \{1, \dots, n\}$
and pick the best solution

$$\max p_i U_{a,D}(t_i) + (1 - p_i)U_{u,D}(t_i) - ax$$

subject to

$$p_j(U_{a,A}(t_j) - x) + (1 - p_j)U_{u,A}(t_j) \leq p_i (U_{a,A}(t_i) - x) + (1 - p_i)U_{u,A}(t_i)$$

$$\forall j \in \{1, \dots, n\}$$

p_i 's lie on the probability simplex

$$0 \leq x \leq 1$$

Adversary's
best response
is attacking
target t_i

Algorithmic Challenges

1. Quadratic constraints

- ▶ $p_i x$ terms

2. Non-convex optimization problem

- ▶ Constraints representable as $x^T A x + Bx + c \leq 0$
- ▶ A is not positive semi-definite

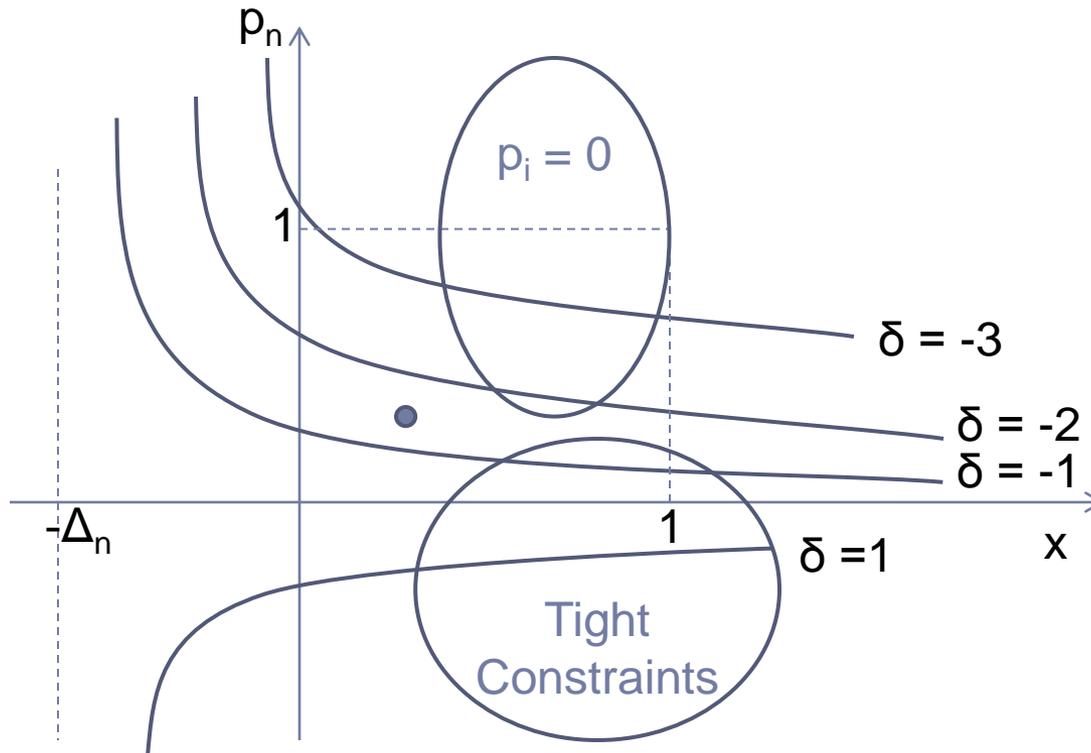
Properties of Optimal Point

► Rewriting quadratic constraints

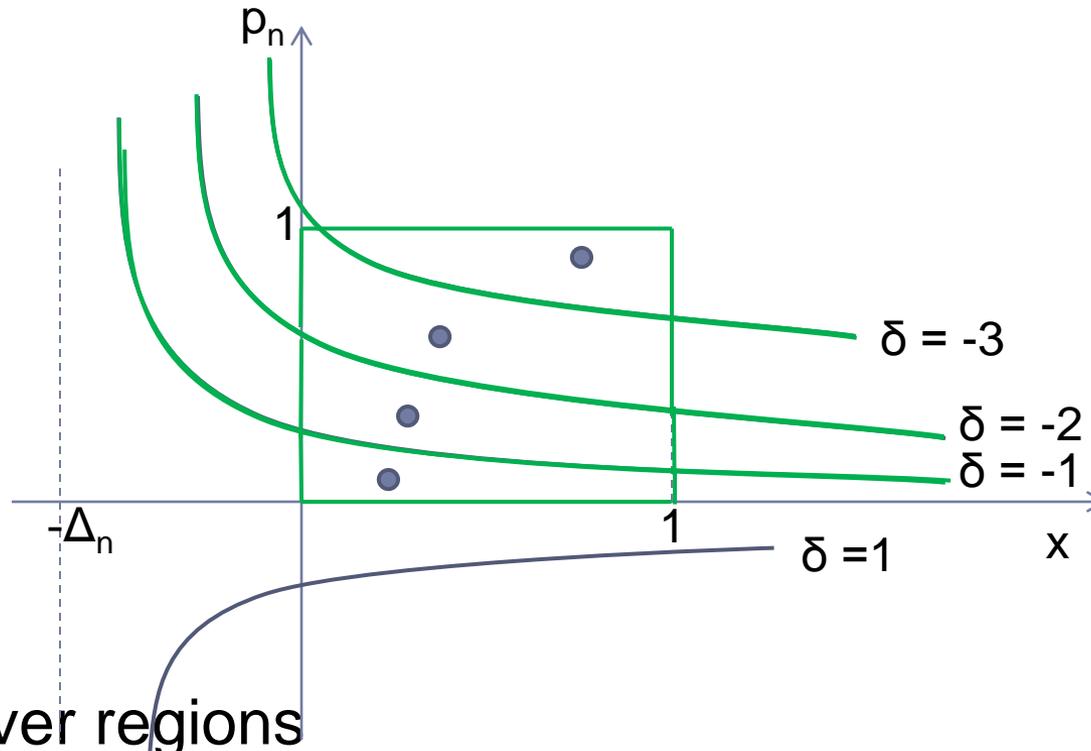
$$p_j(-x - \Delta_j) + p_n(x + \Delta_n) + \delta_{j,n} \leq 0$$

where $\Delta_j \geq 0$

$$\Delta_j = U_{u,A}(t_j) - U_{a,A}(t_j)$$



Overview of Algorithm



- ▶ Iterate over regions
- ▶ Solve sub-problems EQ_j
 - ▶ Set probabilities to zero for curves that lie above & make other constraints tight
- ▶ Pick best solution of all EQ_j

Solving Sub-problem EQ_j

1. $p_j(-x - \Delta_j) + p_n(x + \Delta_n) + \delta_{j,n} = 0$
 - Eliminate p_j to get an equation in p_n and x only
2. Express p_n as a function $f(x)$
 - Objective becomes a polynomial function of x only
3. Compute x where derivative of objective is zero & constraints are satisfied
 - Local maxima
4. Compute x values on the boundary
 - Found by finding intersection of $p_n = f(x)$ with the boundaries
 - Other potential points of maxima
5. Take the maximum over all x values output by Steps 3,4

Steps 3 & 4 require computing roots of polynomials

Computing Roots of Polynomials

- ▶ Using existing algorithms
 - ▶ Splitting circle method [Schonage 1982] can approx. irrational roots to precision K in time polynomial in K
 - ▶ *Steps 3 and 4 take imprecision into account*
 - ▶ LLL [Lenstra et al. 1982] can find rational roots exactly

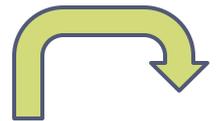
Main Theorem

- ▶ *The problem can be approximated to an additive ϵ factor in time $O(n^5 K + n^4 \log(1/\epsilon))$ using only the splitting circle method, where K is the bit precision of inputs.*
- ▶ Using LLL the time is still polynomial $O(\max\{n^{13}K^3, n^5 K + n^4 \log(1/\epsilon)\})$, and if the solution is rational the exact solution is found.

Play in Three Acts

1. Rational Adversary Setting
2. Byzantine Adversary Setting 
3. Research Directions

[Blocki, Christin, Datta, Sinha; CSF 2011]

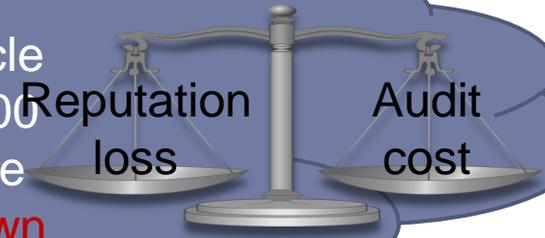


Audit Model



Auditor

Auditing budget: \$3000/ cycle
Cost for one inspection: \$100
Only 30 inspections per cycle
Employee incentives unknown



Access divided into 2 types

Reputation Loss from 1 violation (internal, external)

100 accesses

30 accesses



Sandra Bullock

\$500, \$1000

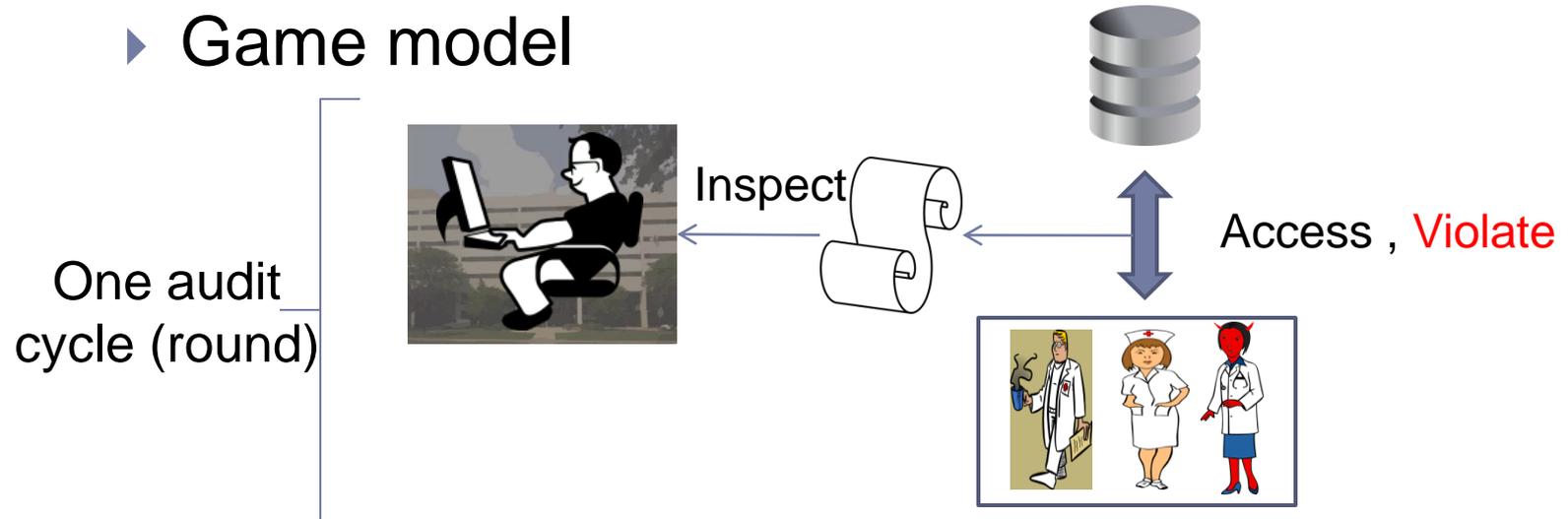
70 accesses



\$250, \$500

Repeated Game Model for Audit

▶ Game model



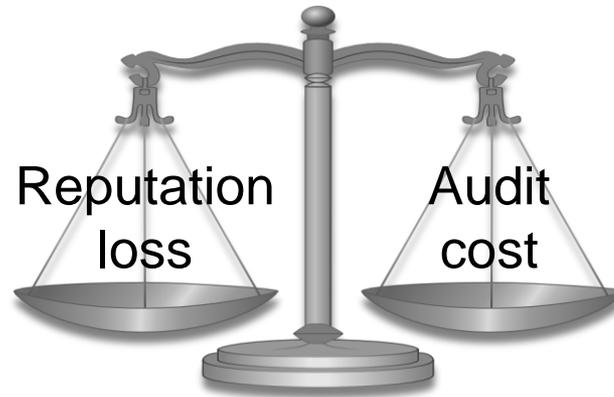
▶ Typical actions in one round

- ▶ Emp action: (access, **violate**) = ([30,70], [2,4])
- ▶ Org action: inspection = ([10,20])

Imperfection
n

Game Payoffs

▶ Organization's payoff



- ▶ Audit cost depends on the number of inspections
- ▶ Reputation loss depends on the number of violations caught

▶ Employee's payoff unknown

Audit Algorithm Choices



Only 30 inspections

Consider 4 possible allocations of the available 30 inspections



Sandra Bullock



Weights

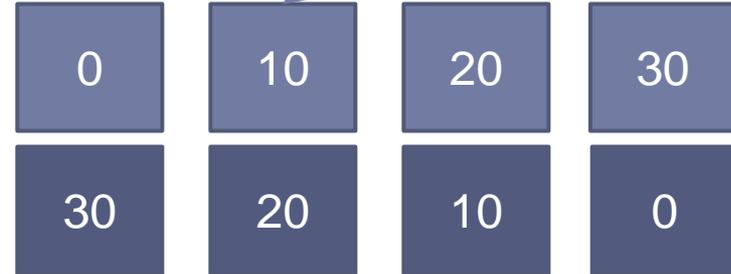
0	10	20	30
30	20	10	0
1.0	1.0	1.0	1.0

Choose allocation probabilistically based on weights

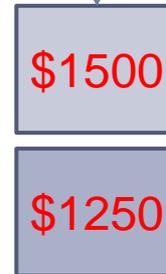
Audit Algorithm Run



No. of Access	Actual Violatio
30	21
70	4



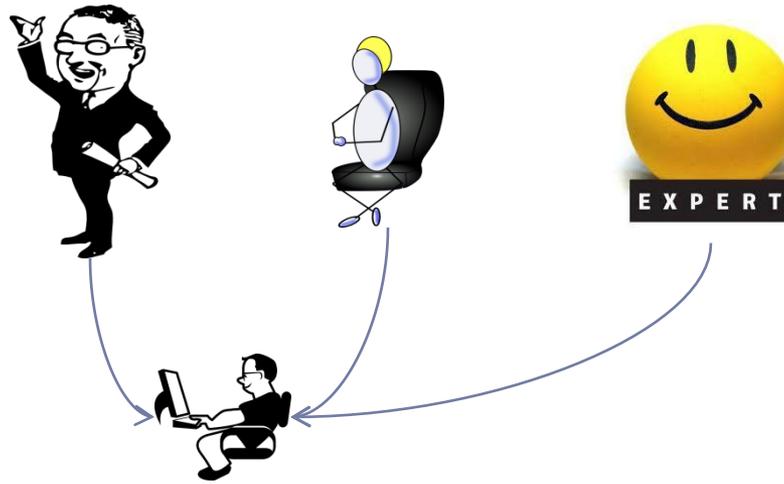
Loss



Int. Caught	Ext. Caught
1	1
2	1



Property of Effective Audit Mechanism



- ▶ Audit mechanism should be comparable to best expert in hindsight
- ▶ Audit: Experts recommend resource allocations

Low Regret

- ▶ Low regret of s w.r.t. s^1 means s performs as well as s^1
- ▶ Desirable property of an audit mechanism
 - ▶ Low regret w.r.t all strategies in a given set of strategies

$$\text{regret} \rightarrow 0 \text{ as } T \rightarrow \infty$$

- ▶ Audit setting
 - ▶ Audit mechanism recommended resource allocation performs as well as best fixed resource allocation in hindsight

Challenges in Audit Setting

- ▶ Sleeping experts
 - ▶ Not all experts available in each audit round (e.g., [300,10] in Figure 1)
- ▶ Imperfect information
 - ▶ In each round, only one expert's advice is followed and associated loss observed
 - ▶ Requires loss estimation for outcome for all other experts

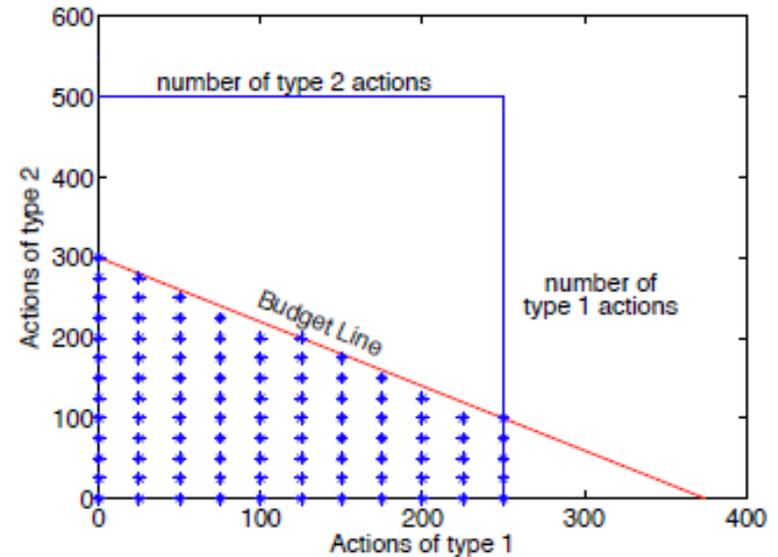
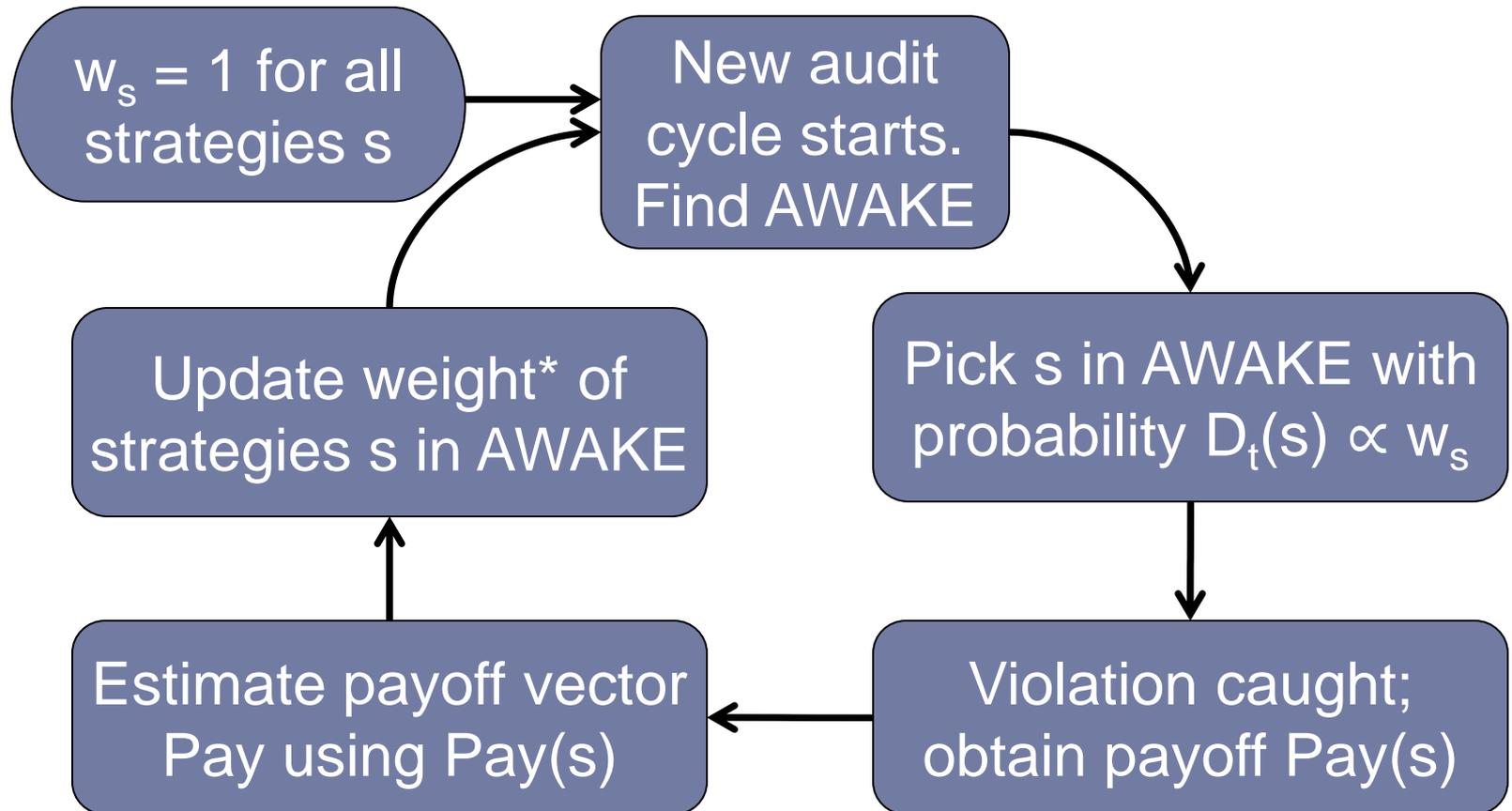


Figure 1. Feasible audit space, represented by the shaded area.

Regret Minimizing Audits (RMA)



$$* w_s \leftarrow w_s \cdot \gamma^{-Pay(s) + \gamma \cdot \sum_{s'} D_t(s') Pay(s')}$$

Audit Algorithm Run



No. of Access	Actual Violatio
30	2
70	4



0	10	20	30
30	20	10	0

Observed Loss

Estimated Loss

Int. Caught	Ext. Caught
1	1
2	1



\$2000	\$1500	\$1000	\$1000
\$750	\$1250	\$1250	\$1500

Updated weights

0.5	0.5	2.0	1.5
-----	-----	-----	-----

Learn from experience: weights updated using observed and estimated loss

Guarantees of RMA

- ▶ With probability $1 - \epsilon$ RMA achieves the regret bound

$$2\sqrt{\frac{2 \ln N}{T}} + \frac{2 \ln N}{T} + 2\sqrt{\frac{2 \ln \left(\frac{4N}{\epsilon}\right)}{T}}$$

- ▶ N is the set of strategies
- ▶ T is the number of rounds
- ▶ All payoffs scaled to lie in $[0, 1]$

Related Work

- ▶ **Weighted Majority Algorithm [LW89]:**
 - ▶ Average Regret: $O((\log N)/T)^{1/2}$
 - ▶ Defender cannot run this algorithm unless he observes the adversaries moves (perfect information setting)

- ▶ **Imperfect Information Setting [ACFS02]:**
 - ▶ Average Regret: $O(((N \log N)/T)^{1/2})$
 - ▶ Regret bound converges to 0 much slower

- ▶ Our regret bounds are of the same order as the perfect information setting assuming loss estimation function is *accurate* and *independent*

Play in Three Acts

1. Rational Adversary Setting
2. Byzantine Adversary Setting
3. Research Directions 

Research Directions

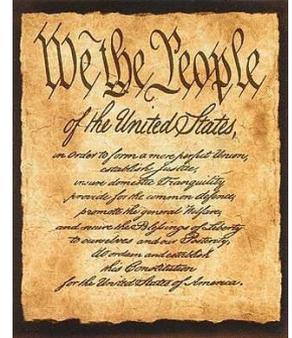
- ▶ **Augmenting model and algorithm**
 - ▶ Repeated interaction
 - ▶ Multiple defender resources constrained by audit budget
 - ▶ Multiple heterogeneous targets attacked by adversary
 - ▶ Information flow violations
 - ▶ Combining rational and byzantine adversary model
- ▶ **Acquiring parameters of model**
 - ▶ Ponemon studies, Verizon data breach reports
- ▶ **From risk management to privacy protection**
 - ▶ Why should organizations invest in audits to protect privacy?
 - ▶ What public policy interventions are most effective in encouraging thorough audits (e.g., HHS audits, data breach notification law)?

Initial
results in
[BCDS'12]

A Research Area

- ▶ Formalize Privacy Policies
 - ▶ Precise definitions of privacy concepts (restrictions on information flow)
 - ▶ Information used *only for a purpose*
 - ▶ All disclosure clauses in HIPAA & GLBA

- ▶ Enforce Privacy Policies
 - ▶ Audit and Accountability
 - ▶ Detect violations of policy
 - ▶ Identify agents to blame for policy violations
 - ▶ **Resource allocation for inspections and punishments (economic considerations)**



Project page: [Privacy, Audit and Accountability](#)

Thanks!
Questions?

Proof of Property of Optimal Point

- ▶ Quadratic constraints

$$p_n(x + \Delta_n) + \delta_{j,n} \leq p_j(x + \Delta_j) \quad \text{where } \Delta_j \geq 0$$

- ▶ Fact 1: p_j is 0 or the j^{th} constraint is tight
- ▶ Fact 2a: if $p_n(x + \Delta_n) + \delta_{j,n} \leq 0$ then p_j is 0
 - ▶ $p_j(x + \Delta_j) \geq 0$, thus the constraint cannot be tight, so p_j is 0
- ▶ Fact 2b: if $p_n(x + \Delta_n) + \delta_{j,n} > 0$ then tight constr
 - ▶ p_j cannot be 0, so constraint has to be tight

Problem P_n

Fortunately, the problem P_n has another property that allows for efficient methods. Let us rewrite P_n in a more compact form. Let $\Delta_{D,i} = U_D^a(t_i) - U_D^u(t_i)$, $\Delta_i = U_A^u(t_i) - U_A^a(t_i)$ and $\delta_{i,j} = U_A^u(t_i) - U_A^u(t_j)$. $\Delta_{D,i}$ and Δ_i are always positive, and P_n reduces to:

$$\begin{aligned} \max_{p_i, x} \quad & p_n \Delta_{D,n} + U_D^u(t_n) - ax, \\ \text{subject to} \quad & \forall i \neq n. p_i(-x - \Delta_i) + p_n(x + \Delta_n) + \delta_{i,n} \leq 0, \\ & \forall i. 0 \leq p_i \leq 1, \\ & \sum_i p_i = 1, \\ & 0 \leq x \leq 1. \end{aligned}$$



Problem $Q_{n,i}$

$$\begin{aligned} & \max_{x, p(1), \dots, p(i), p_n} && p_n \Delta_{D,n} - ax, \\ & \text{subject to} && p_n(x + \Delta_n) + \delta_{(i),n} \geq 0, \\ & && \text{if } i \geq 2 \text{ then } p_n(x + \Delta_n) + \delta_{(i-1),n} < 0, \\ & && \forall j \geq i. p_n(x + \Delta_n) + \delta_{(j),n} = p_{(j)}(x + \Delta_j), \\ & && \forall j > i. 0 < p_{(j)} \leq 1, \\ & && 0 \leq p_{(i)} \leq 1, \\ & && \sum_{k=i}^{n-1} p_{(k)} = 1 - p_n, \\ & && 0 \leq p_n < 1, \\ & && 0 < x \leq 1. \end{aligned}$$



Problem $R_{n,i}$

$$\max_{x, p_n} p_n \Delta_{D,n} - ax ,$$

subject to

$$p_n(x + \Delta_n) + \delta_{(i),n} \geq 0 ,$$

$$\text{if } i \geq 2 \text{ then } p_n(x + \Delta_n) + \delta_{(i-1),n} < 0 ,$$

$$p_n \left(1 + \sum_{j:i \leq j \leq n-1} \frac{x + \Delta_n}{x + \Delta_{(j)}} \right) = 1 - \sum_{j:i \leq j \leq n-1} \frac{\delta_{(j),n}}{x + \Delta_{(j)}} ,$$

$$0 \leq p_n < 1 ,$$

$$0 < x \leq 1 .$$

